

The Lasso with general Gaussian designs and its applications



Yuting Wei

Carnegie Mellon University

JSM, Aug 4th, 2020



Michael Celentano
Stanford Stat

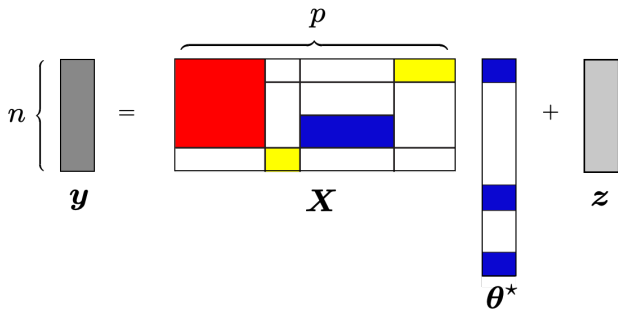


Andrea Montanari
Stanford Stat & EE

“The Lasso with general Gaussian designs with application to hypothesis testing,”

M. Celentano, A. Montanari, Y. Wei, 2020. <https://arxiv.org/abs/2007.13716>

Lasso estimator



$$\hat{\boldsymbol{\theta}} := \arg \min_{\boldsymbol{\theta} \in \mathbb{R}^p} \left\{ \frac{1}{2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|_2^2 + \lambda \|\boldsymbol{\theta}\|_1 \right\} \quad [\text{Tibshirani, 1996}]$$

Prior work: Lasso risk

Suppose θ^* is s -sparse, $z \sim \mathcal{N}(0, \sigma^2 \mathbf{I}_n)$. Under restricted eigenvalue condition of design matrix \mathbf{X} ,

$$\|\hat{\theta} - \theta^*\|_2 \leq C\sigma\sqrt{\frac{s \log(p)}{n}}$$

[Bickel et al., 2009, Bühlmann and Van De Geer, 2011, Negahban et al., 2012, Zhao and Yu, 2006, Zhang and Zhang, 2014, Bellec et al., 2018]...

Prior work: Lasso risk

Suppose θ^* is s -sparse, $z \sim \mathcal{N}(0, \sigma^2 \mathbf{I}_n)$. Under restricted eigenvalue condition of design matrix \mathbf{X} ,

$$\|\hat{\theta} - \theta^*\|_2 \leq C\sigma\sqrt{\frac{s \log(p)}{n}}$$

- unspecified constant

[Bickel et al., 2009, Bühlmann and Van De Geer, 2011, Negahban et al., 2012, Zhao and Yu, 2006, Zhang and Zhang, 2014, Bellec et al., 2018]...

Prior work: Lasso risk

Suppose θ^* is s -sparse, $z \sim \mathcal{N}(0, \sigma^2 \mathbf{I}_n)$. Under restricted eigenvalue condition of design matrix \mathbf{X} ,

$$\|\hat{\theta} - \theta^*\|_2 \leq C\sigma\sqrt{\frac{s \log(p)}{n}}$$

- unspecified constant
- no distributional characterization of $\hat{\theta}$

[Bickel et al., 2009, Bühlmann and Van De Geer, 2011, Negahban et al., 2012, Zhao and Yu, 2006, Zhang and Zhang, 2014, Bellec et al., 2018]...

Prior work: Lasso risk

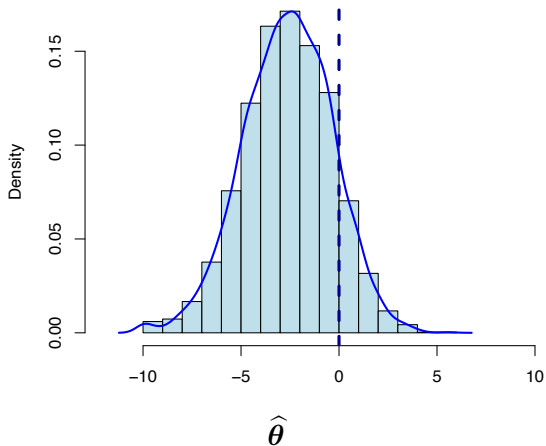
Suppose θ^* is s -sparse, $z \sim \mathcal{N}(0, \sigma^2 \mathbf{I}_n)$. Under restricted eigenvalue condition of design matrix \mathbf{X} ,

$$\|\hat{\theta} - \theta^*\|_2 \leq C\sigma\sqrt{\frac{s \log(p)}{n}}$$

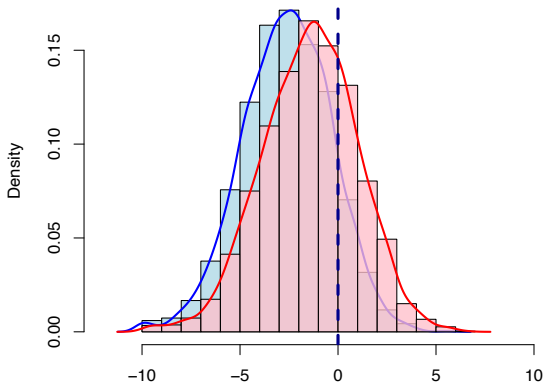
- unspecified constant
- no distributional characterization of $\hat{\theta}$
- inadequate for statistical inference

[Bickel et al., 2009, Bühlmann and Van De Geer, 2011, Negahban et al., 2012, Zhao and Yu, 2006, Zhang and Zhang, 2014, Bellec et al., 2018]...

Prior work: debiased Lasso



Prior work: debiased Lasso

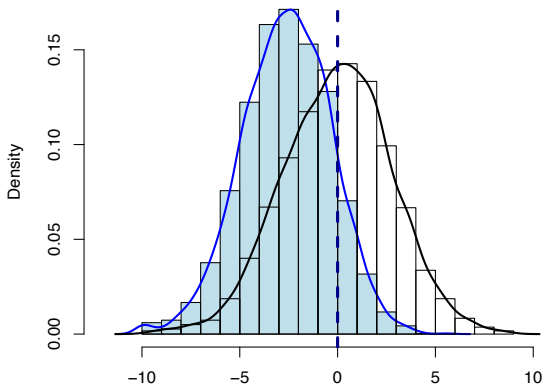


$$\hat{\theta}^d = \hat{\theta} + \mathbf{M}\mathbf{X}^\top(\mathbf{y} - \mathbf{X}\hat{\theta})$$

\mathbf{M} surrogate for $\Sigma^{-1} = \mathbb{E}[\mathbf{x}_i\mathbf{x}_i^\top]^{-1}$

[Zhang and Zhang, 2014, Van de Geer et al., 2014, Javanmard and Montanari, 2014a, Javanmard and Montanari, 2014b]

Prior work: debiased Lasso



$$\hat{\theta}^d = \hat{\theta} + \mathbf{M}\mathbf{X}^\top(\mathbf{y} - \mathbf{X}\hat{\theta})$$

\mathbf{M} scaled version of $\Sigma^{-1} = \mathbb{E}[\mathbf{x}_i\mathbf{x}_i^\top]^{-1}$

[Javanmard et al., 2018, Miolane and Montanari, 2018, Bellec and Zhang, 2019a,
Bellec and Zhang, 2019b]

Inadequacy of current theory

- not applicable for $s/p = \text{const}$ regime
- precise characterization developed for uncorrelated designs
[Javanmard and Montanari, 2014b, Miolane and Montanari, 2018]
- for correlated designs with $n > p$
[Bellec and Zhang, 2019a, Bellec and Zhang, 2019b]

Towards a general design

Prior work: i.i.d. Gaussian design: $\mathbf{x}_i \sim \mathcal{N}(0, \mathbf{I}_p)$

[Bayati and Montanari, 2011, Thrampoulidis et al., 2015, Miolane and Montanari, 2018]

Towards a general design

Prior work: i.i.d. Gaussian design: $\mathbf{x}_i \sim \mathcal{N}(0, \mathbf{I}_p)$

[Bayati and Montanari, 2011, Thrampoulidis et al., 2015, Miolane and Montanari, 2018]

What happens with general Gaussian design $\mathbf{x}_i \sim \mathcal{N}(0, \Sigma)$?

Towards a general design

Prior work: i.i.d. Gaussian design: $\mathbf{x}_i \sim \mathcal{N}(0, \mathbf{I}_p)$

[Bayati and Montanari, 2011, Thrampoulidis et al., 2015, Miolane and Montanari, 2018]

What happens with general Gaussian design $\mathbf{x}_i \sim \mathcal{N}(0, \Sigma)$?

— **difficulty:** non-isometry of $\|\cdot\|_1$ penalty.

This talk

$$\mathbf{y} = \mathbf{X}\boldsymbol{\theta}^* + \mathbf{z} \in \mathbb{R}^n$$

This talk

$$\mathbf{y} = \mathbf{X}\boldsymbol{\theta}^* + \mathbf{z} \in \mathbb{R}^n$$

- $\boldsymbol{\theta}^* \in \mathbb{R}^p$: s -sparse

This talk

$$\mathbf{y} = \mathbf{X}\boldsymbol{\theta}^* + \mathbf{z} \in \mathbb{R}^n$$

- $\boldsymbol{\theta}^* \in \mathbb{R}^p$: s -sparse
- **proportional regime**: $p/n = \text{const}$, $s/p = \text{const}$

This talk

$$\mathbf{y} = \mathbf{X}\boldsymbol{\theta}^* + \mathbf{z} \in \mathbb{R}^n$$

- $\boldsymbol{\theta}^* \in \mathbb{R}^p$: s -sparse
- **proportional regime**: $p/n = \text{const}$, $s/p = \text{const}$
- Gaussian noise: $\mathbf{z} \sim \mathcal{N}(0, \sigma^2 \mathbf{I}_n)$; Gaussian design: $\mathbf{x}_i \sim \mathcal{N}(0, \underbrace{\boldsymbol{\Sigma}}_{\text{known}})$

This talk

$$\mathbf{y} = \mathbf{X}\boldsymbol{\theta}^* + \mathbf{z} \in \mathbb{R}^n$$

- $\boldsymbol{\theta}^* \in \mathbb{R}^p$: s -sparse
- **proportional regime**: $p/n = \text{const}$, $s/p = \text{const}$
- Gaussian noise: $\mathbf{z} \sim \mathcal{N}(0, \sigma^2 \mathbf{I}_n)$; Gaussian design: $\mathbf{x}_i \sim \mathcal{N}(0, \underbrace{\boldsymbol{\Sigma}}_{\text{known}})$

Goal: a distributional theory for general Gaussian design

Key observation

original model

$\hat{\theta}$

- **original model:** $\mathbf{y} = \mathbf{X}\theta + \mathbf{z}$

$$\hat{\theta} := \arg \min_{\theta \in \mathbb{R}^p} \left\{ \frac{1}{2} \|\mathbf{y} - \mathbf{X}\theta\|_2^2 + \lambda \|\theta\|_1 \right\}$$

Key observation

original model

$$\hat{\boldsymbol{\theta}}$$

fixed design model

$$\hat{\boldsymbol{\theta}}^f$$

- **original model:** $\mathbf{y} = \mathbf{X}\boldsymbol{\theta} + \mathbf{z}$

$$\hat{\boldsymbol{\theta}} := \arg \min_{\boldsymbol{\theta} \in \mathbb{R}^p} \left\{ \frac{1}{2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|_2^2 + \lambda \|\boldsymbol{\theta}\|_1 \right\}$$

- **fixed design model:** $\mathbf{y}^f = \boldsymbol{\Sigma}^{1/2}\boldsymbol{\theta}^* + \tau^* \mathbf{g}$, $\mathbf{g} \sim \mathcal{N}(0, \mathbf{I}_p)$

$$\hat{\boldsymbol{\theta}}^f := \arg \min_{\boldsymbol{\theta} \in \mathbb{R}^p} \left\{ \frac{\zeta^*}{2} \|\mathbf{y}^f - \boldsymbol{\Sigma}^{1/2}\boldsymbol{\theta}\|_2^2 + \lambda \|\boldsymbol{\theta}\|_1 \right\}$$

Key observation

original model

$$\hat{\theta}$$

fixed design model

$$\hat{\theta}^f$$

- **original model:** $\mathbf{y} = \mathbf{X}\boldsymbol{\theta} + \mathbf{z}$

$$\hat{\theta} := \arg \min_{\boldsymbol{\theta} \in \mathbb{R}^p} \left\{ \frac{1}{2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|_2^2 + \lambda \|\boldsymbol{\theta}\|_1 \right\}$$

- **fixed design model:** $\mathbf{y}^f = \boldsymbol{\Sigma}^{1/2}\boldsymbol{\theta}^* + \boldsymbol{\tau}^* \mathbf{g}$, $\mathbf{g} \sim \mathcal{N}(0, \mathbf{I}_p)$

$$\hat{\theta}^f := \arg \min_{\boldsymbol{\theta} \in \mathbb{R}^p} \left\{ \frac{\zeta^*}{2} \|\mathbf{y}^f - \boldsymbol{\Sigma}^{1/2}\boldsymbol{\theta}\|_2^2 + \lambda \|\boldsymbol{\theta}\|_1 \right\}$$

$\boldsymbol{\tau}^*$: effective risk level; ζ^* : effective non-sparsity

Key observation

original model

$\hat{\theta}$

distribution

\approx

fixed design model

$\hat{\theta}^f$

- **original model:** $\mathbf{y} = \mathbf{X}\boldsymbol{\theta} + \mathbf{z}$

$$\hat{\theta} := \arg \min_{\boldsymbol{\theta} \in \mathbb{R}^p} \left\{ \frac{1}{2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|_2^2 + \lambda \|\boldsymbol{\theta}\|_1 \right\}$$

- **fixed design model:** $\mathbf{y}^f = \boldsymbol{\Sigma}^{1/2}\boldsymbol{\theta}^* + \boldsymbol{\tau}^* \mathbf{g}$, $\mathbf{g} \sim \mathcal{N}(0, \mathbf{I}_p)$

$$\hat{\theta}^f := \arg \min_{\boldsymbol{\theta} \in \mathbb{R}^p} \left\{ \frac{\zeta^*}{2} \|\mathbf{y}^f - \boldsymbol{\Sigma}^{1/2}\boldsymbol{\theta}\|_2^2 + \lambda \|\boldsymbol{\theta}\|_1 \right\}$$

$\boldsymbol{\tau}^*$: effective risk level; ζ^* : effective non-sparsity

Fixed point equations

(τ^*, ζ^*)

solution
→

$$\tau^2 = \sigma^2 + R(\tau^2, \zeta)$$

$$\zeta = 1 - df(\tau^2, \zeta)$$

Fixed point equations

$$\begin{array}{ccc} (\tau^*, \zeta^*) & \xrightarrow{\text{solution}} & \begin{array}{l} \tau^2 = \sigma^2 + R(\tau^2, \zeta) \\ \zeta = 1 - \text{df}(\tau^2, \zeta) \end{array} \end{array}$$

$$R(\tau^2, \zeta) := \frac{1}{n} \mathbb{E} \left[\underbrace{\|\Sigma^{1/2}(\hat{\theta}^f(\tau, \zeta) - \theta^*)\|_2^2}_{\text{in-sample prediction risk}} \right]$$

$$\text{df}(\tau^2, \zeta) := \frac{1}{n} \mathbb{E} \left[\underbrace{\|\hat{\theta}^f(\tau, \zeta)\|_0}_{\text{degrees of freedom}} \right]$$

Fixed point equations

$$\begin{array}{ccc} (\tau^*, \zeta^*) & \xrightarrow{\text{solution}} & \begin{array}{l} \tau^2 = \sigma^2 + R(\tau^2, \zeta) \\ \zeta = 1 - \text{df}(\tau^2, \zeta) \end{array} \end{array}$$

$$R(\tau^2, \zeta) := \frac{1}{n} \mathbb{E} \left[\underbrace{\|\Sigma^{1/2}(\hat{\theta}^f(\tau, \zeta) - \theta^*)\|_2^2}_{\text{in-sample prediction risk}} \right]$$

$$\text{df}(\tau^2, \zeta) := \frac{1}{n} \mathbb{E} \left[\underbrace{\|\hat{\theta}^f(\tau, \zeta)\|_0}_{\text{degrees of freedom}} \right]$$

Property: solution is unique and bounded for reasonably sparse θ^* .

Main result: Lasso distribution

Theorem (Celetano, Montanari, Wei '20)

Under mild conditions, for any 1-Lipschitz function ϕ and $\epsilon > 0$

$$\forall \lambda \in [\lambda_{\min}, \lambda_{\max}], \quad \left| \phi\left(\frac{\hat{\theta}_{\lambda}}{\sqrt{p}}, \frac{\theta^*}{\sqrt{p}}\right) - \mathbb{E}\left[\phi\left(\frac{\hat{\theta}_{\lambda}^f}{\sqrt{p}}, \frac{\theta^*}{\sqrt{p}}\right)\right] \right| \leq \epsilon,$$

with probability at least $1 - \frac{C}{\epsilon^4} e^{-c n \epsilon^4}$.

Main result: Lasso distribution

Theorem (Celetano, Montanari, Wei '20)

Under mild conditions, for any 1-Lipschitz function ϕ and $\epsilon > 0$

$$\forall \lambda \in [\lambda_{\min}, \lambda_{\max}], \quad \left| \phi\left(\frac{\hat{\theta}_{\lambda}}{\sqrt{\rho}}, \frac{\theta^*}{\sqrt{\rho}}\right) - \mathbb{E}\left[\phi\left(\frac{\hat{\theta}_{\lambda}^f}{\sqrt{\rho}}, \frac{\theta^*}{\sqrt{\rho}}\right)\right] \right| \leq \epsilon,$$

with probability at least $1 - \frac{C}{\epsilon^4} e^{-c n \epsilon^4}$.

A direct consequence:

$$\forall \lambda \in [\lambda_{\min}, \lambda_{\max}], \quad \|\hat{\theta}_{\lambda} - \theta^*\|_2 \approx \mathbb{E}\left[\|\hat{\theta}_{\lambda}^f - \theta^*\|_2\right]$$

Main result: properties for Lasso

- Lasso residual

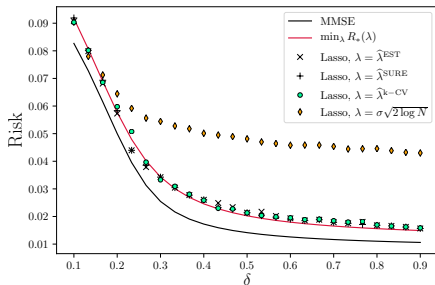
$$\mathbb{P} \left(\left| \frac{\|\mathbf{y} - \mathbf{X}\hat{\boldsymbol{\theta}}\|_2}{\sqrt{n}} - \tau^* \zeta^* \right| > \epsilon \right) \leq \frac{C}{\epsilon^2} e^{-c n \epsilon^4}.$$

- Lasso sparsity

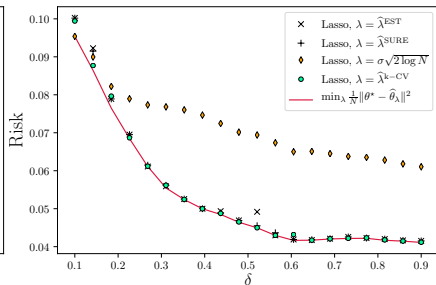
$$\mathbb{P} \left(\left| \frac{\|\hat{\boldsymbol{\theta}}\|_0}{n} - (1 - \zeta^*) \right| > \epsilon \right) \leq \frac{C}{\epsilon^3} e^{-c n \epsilon^6}.$$

Application: model selection

λ selection: $\hat{\lambda}^{\text{EST}} := \min_{\lambda} \hat{\tau}(\lambda) := \frac{\sqrt{n} \|\mathbf{y} - \mathbf{X}\hat{\boldsymbol{\theta}}\|_2}{n - \underbrace{\|\hat{\boldsymbol{\theta}}\|_0}_{\text{degrees of freedom}}}$



(a) Independent columns



(b) Correlated columns

[Miolane and Montanari, 2018]

Debiased Lasso

- classical debiased Lasso

$$\hat{\theta}_0^d = \hat{\theta} + \mathbf{M}\mathbf{X}^\top(\mathbf{y} - \mathbf{X}\hat{\theta}), \quad \mathbf{M} = \Sigma^{-1}$$

Debiased Lasso

- classical debiased Lasso

$$\hat{\theta}_0^d = \hat{\theta} + \mathbf{M}\mathbf{X}^\top(\mathbf{y} - \mathbf{X}\hat{\theta}), \quad \mathbf{M} = \Sigma^{-1}$$

- debiased Lasso with degrees-of-freedom (DOF) adjustment

$$\hat{\theta}^d := \hat{\theta} + \mathbf{M}\mathbf{X}^\top(\mathbf{y} - \mathbf{X}\hat{\theta}), \quad \mathbf{M} = \frac{\Sigma^{-1}}{1 - \|\hat{\theta}\|_0/n}$$

[Javanmard and Montanari, 2014b, Miolane and Montanari, 2018, Bellec and Zhang, 2019a, Bellec and Zhang, 2019b]

Main result: $\hat{\theta}^d$ behaves like $\theta^* + \tau^* \Sigma^{-1/2} \mathbf{g}$

Intuition for DOF adjustment

- **original model:** $\mathbf{y} = \mathbf{X}\boldsymbol{\theta} + \mathbf{z}$

$$\hat{\boldsymbol{\theta}} := \arg \min_{\boldsymbol{\theta} \in \mathbb{R}^p} \left\{ \frac{1}{2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|_2^2 + \lambda \|\boldsymbol{\theta}\|_1 \right\}$$

- **fixed design model:** $\mathbf{y}^f = \boldsymbol{\Sigma}^{1/2}\boldsymbol{\theta}^* + \boldsymbol{\tau}^*\mathbf{g}$

$$\hat{\boldsymbol{\theta}}^f := \arg \min_{\boldsymbol{\theta} \in \mathbb{R}^p} \left\{ \frac{\zeta^*}{2} \|\mathbf{y}^f - \boldsymbol{\Sigma}^{1/2}\boldsymbol{\theta}\|_2^2 + \lambda \|\boldsymbol{\theta}\|_1 \right\}$$

Intuition for DOF adjustment

- **original model:** $\mathbf{y} = \mathbf{X}\boldsymbol{\theta} + \mathbf{z}$

$$\hat{\boldsymbol{\theta}} := \arg \min_{\boldsymbol{\theta} \in \mathbb{R}^p} \left\{ \frac{1}{2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|_2^2 + \lambda \|\boldsymbol{\theta}\|_1 \right\}$$

- **fixed design model:** $\mathbf{y}^f = \boldsymbol{\Sigma}^{1/2}\boldsymbol{\theta}^* + \boldsymbol{\tau}^*\mathbf{g}$

$$\hat{\boldsymbol{\theta}}^f := \arg \min_{\boldsymbol{\theta} \in \mathbb{R}^p} \left\{ \frac{\zeta^*}{2} \|\mathbf{y}^f - \boldsymbol{\Sigma}^{1/2}\boldsymbol{\theta}\|_2^2 + \lambda \|\boldsymbol{\theta}\|_1 \right\}$$

$$\hat{\boldsymbol{\theta}}^d := \hat{\boldsymbol{\theta}} + \frac{\boldsymbol{\Sigma}^{-1}\mathbf{X}^\top(\mathbf{y} - \mathbf{X}\hat{\boldsymbol{\theta}})}{1 - \|\hat{\boldsymbol{\theta}}\|_0/n}$$

Intuition for DOF adjustment

- **original model:** $\mathbf{y} = \mathbf{X}\boldsymbol{\theta} + \mathbf{z}$

$$\hat{\boldsymbol{\theta}} := \arg \min_{\boldsymbol{\theta} \in \mathbb{R}^p} \left\{ \frac{1}{2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|_2^2 + \lambda \|\boldsymbol{\theta}\|_1 \right\}$$

- **fixed design model:** $\mathbf{y}^f = \boldsymbol{\Sigma}^{1/2}\boldsymbol{\theta}^* + \boldsymbol{\tau}^*\mathbf{g}$

$$\hat{\boldsymbol{\theta}}^f := \arg \min_{\boldsymbol{\theta} \in \mathbb{R}^p} \left\{ \frac{\zeta^*}{2} \|\mathbf{y}^f - \boldsymbol{\Sigma}^{1/2}\boldsymbol{\theta}\|_2^2 + \lambda \|\boldsymbol{\theta}\|_1 \right\}$$

$$\hat{\boldsymbol{\theta}}^d := \hat{\boldsymbol{\theta}} + \frac{\boldsymbol{\Sigma}^{-1}\mathbf{X}^\top(\mathbf{y} - \mathbf{X}\hat{\boldsymbol{\theta}})}{1 - \|\hat{\boldsymbol{\theta}}\|_0/n}$$

Intuition for DOF adjustment

- **original model:** $\mathbf{y} = \mathbf{X}\boldsymbol{\theta} + \mathbf{z}$

$$\hat{\boldsymbol{\theta}} := \arg \min_{\boldsymbol{\theta} \in \mathbb{R}^p} \left\{ \frac{1}{2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|_2^2 + \lambda \|\boldsymbol{\theta}\|_1 \right\}$$

- **fixed design model:** $\mathbf{y}^f = \boldsymbol{\Sigma}^{1/2}\boldsymbol{\theta}^* + \boldsymbol{\tau}^*\mathbf{g}$

$$\hat{\boldsymbol{\theta}}^f := \arg \min_{\boldsymbol{\theta} \in \mathbb{R}^p} \left\{ \frac{\zeta^*}{2} \|\mathbf{y}^f - \boldsymbol{\Sigma}^{1/2}\boldsymbol{\theta}\|_2^2 + \lambda \|\boldsymbol{\theta}\|_1 \right\}$$

$$\boldsymbol{\Sigma}^{-1} \cdot \zeta^* \boldsymbol{\Sigma}^{1/2} (\mathbf{y}^f - \boldsymbol{\Sigma}^{1/2} \hat{\boldsymbol{\theta}}^f) = \zeta^* (\boldsymbol{\Sigma}^{-1/2} \mathbf{y}^f - \hat{\boldsymbol{\theta}}^f)$$

$$\hat{\boldsymbol{\theta}}^d := \hat{\boldsymbol{\theta}} + \frac{\boldsymbol{\Sigma}^{-1} \mathbf{X}^\top (\mathbf{y} - \mathbf{X} \hat{\boldsymbol{\theta}})}{1 - \|\hat{\boldsymbol{\theta}}\|_0 / n}$$

Intuition for DOF adjustment

- **original model:** $\mathbf{y} = \mathbf{X}\boldsymbol{\theta} + \mathbf{z}$

$$\hat{\boldsymbol{\theta}} := \arg \min_{\boldsymbol{\theta} \in \mathbb{R}^p} \left\{ \frac{1}{2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|_2^2 + \lambda \|\boldsymbol{\theta}\|_1 \right\}$$

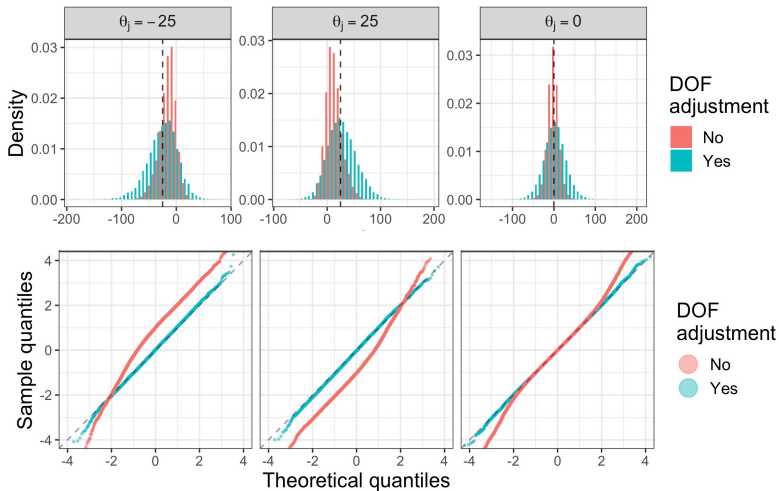
- **fixed design model:** $\mathbf{y}^f = \boldsymbol{\Sigma}^{1/2}\boldsymbol{\theta}^* + \boldsymbol{\tau}^*\mathbf{g}$

$$\hat{\boldsymbol{\theta}}^f := \arg \min_{\boldsymbol{\theta} \in \mathbb{R}^p} \left\{ \frac{\zeta^*}{2} \|\mathbf{y}^f - \boldsymbol{\Sigma}^{1/2}\boldsymbol{\theta}\|_2^2 + \lambda \|\boldsymbol{\theta}\|_1 \right\}$$

$$\boldsymbol{\Sigma}^{-1} \cdot \zeta^* \boldsymbol{\Sigma}^{1/2} (\mathbf{y}^f - \boldsymbol{\Sigma}^{1/2} \hat{\boldsymbol{\theta}}^f) = \zeta^* (\boldsymbol{\Sigma}^{-1/2} \mathbf{y}^f - \hat{\boldsymbol{\theta}}^f)$$

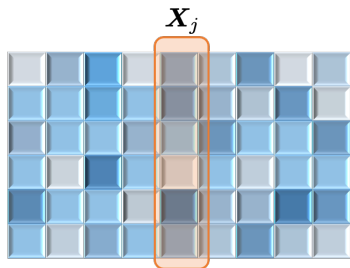
$$\hat{\boldsymbol{\theta}}^d := \hat{\boldsymbol{\theta}} + \frac{\boldsymbol{\Sigma}^{-1} \mathbf{X}^\top (\mathbf{y} - \mathbf{X} \hat{\boldsymbol{\theta}})}{1 - \|\hat{\boldsymbol{\theta}}\|_0 / n} \approx \boldsymbol{\theta}^* + \boldsymbol{\tau}^* \boldsymbol{\Sigma}^{-1/2} \mathbf{g}$$

Debiased Lasso with DOF adjustment



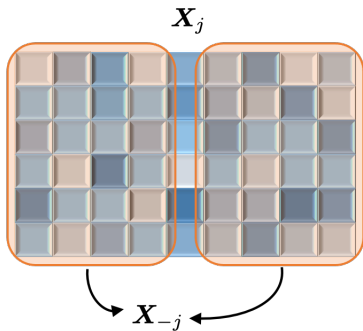
Here $p = 100$, $n = 25$, $s = 20$, $\Sigma_{ij} = 0.5^{|i-j|}$, $\sigma = 1$

Confidence interval for a single coordinate



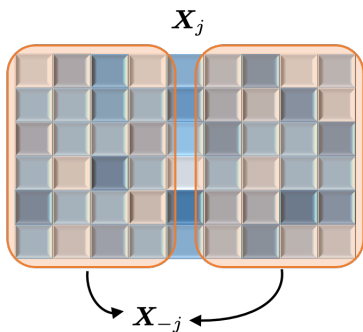
- regress X_j on X_{-j}

Confidence interval for a single coordinate



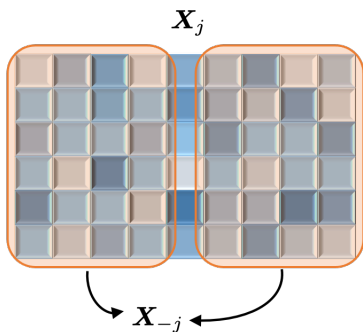
- regress X_j on X_{-j}

Confidence interval for a single coordinate



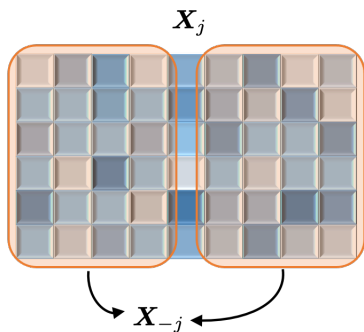
- regress X_j on X_{-j} \longrightarrow residual X_j^\perp

Confidence interval for a single coordinate



- regress X_j on X_{-j} \longrightarrow residual X_j^\perp
- obtain **leave- j^{th} -coordinate-out** Lasso $\hat{\theta}_{100}$

Confidence interval for a single coordinate

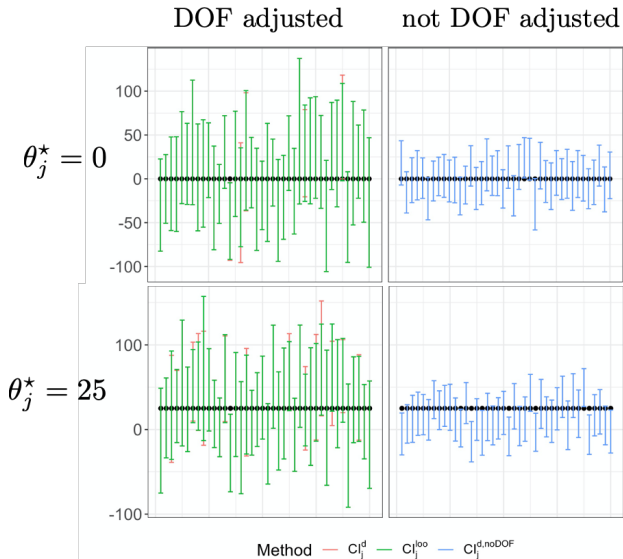


- regress X_j on X_{-j} \longrightarrow residual X_j^\perp
- obtain **leave- j^{th} -coordinate-out** Lasso $\hat{\theta}_{100}$
- construct confidence interval

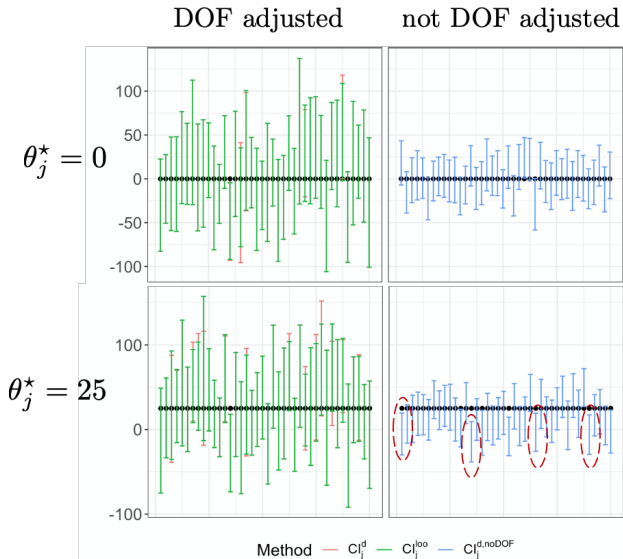
$$CI_j^{100} := [\xi_j \pm \hat{sd} \cdot z_{1-\alpha/2}]$$

ξ_j = correlation between X_j^\perp and $y - X_{-j}\hat{\theta}_{100}$

Confidence interval for a single coordinate



Confidence interval for a single coordinate



Concluding remarks

Summary

- distributional theory of Lasso under general Gaussian design
- applications
 - ▶ theoretical support for model selection
 - ▶ study debiased Lasso and propose single confidence interval

Concluding remarks

Summary

- distributional theory of Lasso under general Gaussian design
- applications
 - ▶ theoretical support for model selection
 - ▶ study debiased Lasso and propose single confidence interval

Future directions

- distributional theory beyond Gaussian design
[[Bayati et al., 2015](#), [Oymak and Tropp, 2018](#), [Montanari and Nguyen, 2017](#)]
- theoretical limit if Σ is unknown

Concluding remarks

Summary

- distributional theory of Lasso under general Gaussian design
- applications
 - ▶ theoretical support for model selection
 - ▶ study debiased Lasso and propose single confidence interval

Future directions

- distributional theory beyond Gaussian design
[Bayati et al., 2015, Oymak and Tropp, 2018, Montanari and Nguyen, 2017]
- theoretical limit if Σ is unknown

“The Lasso with general Gaussian designs with application to hypothesis testing,”

M. Celentano, A. Montanari, Y. Wei, 2020. <https://arxiv.org/abs/2007.13716>