# Minimum $\ell_1$ -norm interpolators: Precise asymptotics and multiple descent



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### Successes of deep neural networks





**Figure**: training deep neural networks (DNN)  $f(x; \theta) = \sigma(W_L \cdot \sigma(W_{L-1} \cdots \sigma(W_1 \cdot x)))$ 

- implicit algorithmic benefit by stochastic gradient methods
- training data is of enormous size (in # samples and # dimensions)
- networks are greatly overparametrized (large depth and width)
- networks are trained beyond zero training error

# Empirical evidence: Larger models are better



Figure: Nakkiran et al. 2019

See also: Opper (1995, 2001), Neyshabur et al. (2014), Canziani et al. (2016), Advani and Saxe (2017), Spigler et al. (2018), Novak et al. (2018), Geiger et al. (2019), ...

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Question: how do these networks manage to generalize?

### **Classical bias-variance trade-off**



"The elements of statistical learning" by Hastie, Tibshirani, Friedman

### Reconcile bias-variance trade-off

— a curious *double-descent* phenomenon



Figure: Belkin, Hsu, Ma, Mandal (2019)

### Reconcile bias-variance trade-off

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It motivates us to study classical estimators in the modern interpolating regime when interpolation happens! So far, theoretical understandings are limited...

# Limited theoretical understanding

Minimum  $\ell_2$ -norm interpolators

$$\widehat{\boldsymbol{\theta}}^{\ell_{2}} \coloneqq \arg\min_{\boldsymbol{\theta} \in \mathbb{R}^{p}} \left\{ \frac{1}{2} \|\boldsymbol{y} - \boldsymbol{X}\boldsymbol{\theta}\|_{2}^{2} + \lambda \|\boldsymbol{\theta}\|_{2}^{2} \right\} \qquad (\lambda \to 0, \ n = \Omega(p))$$

$$n \left\{ \boxed{\boldsymbol{y}} = \underbrace{\boldsymbol{y}}_{\boldsymbol{X}} + \underbrace{\boldsymbol{z}}_{\boldsymbol{\theta}^{\star}} \right\}$$

Belkin et al. (2019), Hastie et al. (2019), Mei and Montanari (2019), Muthukumar et al. (2020), Liang and Rakhlin (2020), Belkin et al. (2020), Bartlett et al. (2020, 2021), ...



Figure: (left) ridgeless regression for misspecified model Hastie, Montanari, Rosset, Tibshirani (2019), (right) random features regression with ReLU activation Mei and Montanari (2019)

- resemble the lazy training regime of 2-layer neural nets

#### Question: how about other interpolators?

$$\text{for example:} \quad \widehat{\boldsymbol{\theta}}^{\ell_{\mathbf{q}}} \coloneqq \arg\min_{\boldsymbol{\theta} \in \mathbb{R}^p} \frac{1}{2} \|\boldsymbol{y} - \boldsymbol{X}\boldsymbol{\theta}\|_2^2 + \lambda \|\boldsymbol{\theta}\|_q^q \quad (\lambda \to 0, n = \Omega(p))$$



•  $\ell_1$  penalty encourages sparse solution (for interpretability)



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- empirical successes of dropouts/model-pruning in DL Srivastava, Hinton, et al. (2014), Ye et al. (2020)

### **Basis Pursuit for noiseless observations**



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Chen et al. 2001, Wojtaszczyk, Candes and Tao 2006, Donoho 2006, Donoho et al. 2005, Donoho and Tanner 2009, Amelunxen et al. 2014, Ju et al. 2020, Chinot et al. 2020, Wang et al. 2021, ...

## **Basis Pursuit for noiseless observations**



In the noisy and over-parametrized case (p > n), how does generalization error of min  $\ell_1$  solution depend on p/n?

### A multi-descent phenomenon



**Figure:** Multiple descent in sparse linear regression. Let the true signal  $\theta^*$  be an *s*-sparse vector, where *M* is the magnitude of non-zero entries. Fix s/n = 0.3 and  $s/n \cdot M^2 = 10$ . Set the sample size as n = 100, and choose 500 values of p/n.

### A multi-descent phenomenon



Figure: Multiple descent in sparse linear regression. Let the true signal  $\theta^*$  be an *s*-sparse vector, where  $\sqrt{\delta}M$  is the magnitude of non-zero entries. Fix s/p = 0.01 and  $s/p \cdot M^2 = 2$ . Set the sample size as n = 100, and choose 500 values of p/n.

• How to theoretically characterize these descents ?

as a function of  $\ensuremath{\boldsymbol{p}}\xspace/n$ 

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#### Challenges:

- no closed-form solutions for min  $\ell_1$ -norm interpolators
- no consistent support recovery in high dimensional regime
- *no* strong convexity in this optimization problem



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- proportional regime:  $s/p = \epsilon$  (const),  $n/p = \delta$  (const)
- Gaussian design and Gaussian noise

$$\boldsymbol{x}_i \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}\left(0, \frac{1}{n} \boldsymbol{I}_p\right), \qquad z_i \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, \sigma^2)$$

# Exact asymptotics framework

min 
$$\ell_1$$
-norm interpolator  $(n < p)$   
 $\widehat{\boldsymbol{\theta}}^{\text{Int}} \coloneqq \underset{\boldsymbol{\theta} \in \mathbb{R}^p}{\operatorname{emm}} \|\boldsymbol{\theta}\|_1$  subject to  $y_i = \langle \boldsymbol{x}_i, \boldsymbol{\theta} \rangle, \quad 1 \le i \le n$ 

• generalization error:

$$\mathsf{Risk}(\widehat{\boldsymbol{\theta}}^{\mathsf{Int}}) \coloneqq \mathbb{E}\left[(\boldsymbol{x}_{\mathsf{new}}^{\top} \widehat{\boldsymbol{\theta}}^{\mathsf{Int}} - y_{\mathsf{new}})^2\right] = \frac{1}{n} \|\widehat{\boldsymbol{\theta}}^{\mathsf{Int}} - \boldsymbol{\theta}^{\star}\|_2^2 + \sigma^2$$

# Exact asymptotics framework

 $\begin{array}{l} \min \ \ell_1 \text{-norm interpolator } (n < p) \\ \widehat{\boldsymbol{\theta}}^{\mathsf{Int}} \coloneqq \arg\min_{\boldsymbol{\theta} \in \mathbb{R}^p} \|\boldsymbol{\theta}\|_1 \quad \text{ subject to } \quad y_i = \langle \boldsymbol{x}_i, \ \boldsymbol{\theta} \rangle, \quad 1 \leq i \leq n \end{array}$ 

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• high-dim asymptotics ( $\delta = n/p, \ \epsilon = s/p$ )

$$\mathsf{Risk}(\widehat{\theta}^{\mathsf{Int}}, \delta) = \lim_{\substack{n/p = \delta \\ n, p \to \infty}} \mathsf{Risk}(\widehat{\theta}^{\mathsf{Int}}) = ???$$

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• how does  $\operatorname{Risk}(\widehat{\theta}^{\operatorname{Int}}, \delta)$  vary as a function of  $\delta$ ?

# An incomplete literature list on exact asymptotics

$$\mathsf{Risk}(\widehat{\theta}^{\mathsf{Int}}, \delta) = \lim_{\substack{n/p = \delta \\ n, p \to \infty}} \mathsf{Risk}(\widehat{\theta}^{\mathsf{Int}}) = ???$$

• compressed sensing and Lasso estimators

Donoho, Maleki and Montanari (2009), Bayati and Montanari (2011), Stojnic (2013), Oymak et al. (2013), Miolane and Montanari (2018), Bellec and Zhang (2019), Celentano, Montanari and Wei (2020)

robust regression and ridge regreesion
 Donoho and Montanari (2016), El Karoui (2013, 2018), Thrampoulidis et al. (2018),
 Dobriban and Wager (2018), Hastie et al. (2019), Mei and Montanari (2019), Patil et al. (2021)

#### classification

Sur, Chen and Candés (2017), Montanari et al. (2019), Liang and Sur (2020), Javanmard and Soltanolkotabi (2020)

### Main result: Risk curve for min $\ell_1$ solution

Suppose  $\theta_i^{\star} \stackrel{\text{i.i.d.}}{\sim} \epsilon \mathcal{P}_{M\sqrt{\delta}} + (1-\epsilon)\mathcal{P}_0 \ (SNR = \frac{1}{\sigma^2} \mathbb{E}(\boldsymbol{x}_i^{\top} \boldsymbol{\theta}^{\star})^2 = \frac{\epsilon M^2}{\sigma^2})$ 

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Theorem (Li, W' 21)

•  $\mathsf{Risk}(\widehat{\theta}^{\mathsf{Int}}; \delta) \to \mathsf{Risk}(\mathbf{0}) \text{ as } p/n \text{ tends to } \infty.$ 


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#### Theorem (Li, W' 21)

- $\mathsf{Risk}(\widehat{\theta}^{\mathsf{Int}}; \delta) \to \mathsf{Risk}(\mathbf{0}) \text{ as } p/n \text{ tends to } \infty.$
- for every given  $\delta$ , there exists  $\tilde{\epsilon}(\delta)$  st.  $\operatorname{Risk}(\widehat{\theta}^{\operatorname{Int}}; \delta)$  decreases with p/n at  $\delta$  as long as the sparsity ratio  $\epsilon$  satisfies  $\epsilon \leq \tilde{\epsilon}(\delta)$ .



### Main result: Risk curve shape (continued)

Suppose 
$$\theta_i^{\star} \stackrel{\text{i.i.d.}}{\sim} \epsilon \mathcal{P}_{M\sqrt{\delta}} + (1-\epsilon)\mathcal{P}_0 \ (SNR = \frac{1}{\sigma^2} \mathbb{E}(\boldsymbol{x}_i^{\top} \boldsymbol{\theta}^{\star})^2 = \frac{\epsilon M^2}{\sigma^2})$$

#### Theorem (Li, W '21)

there exist two constants 1 < η<sub>1</sub> < η<sub>2</sub> < ∞ st. Risk(θ<sup>lnt</sup>; δ) decreases with p/n within the range p/n ∈ (1, η<sub>1</sub>) ∪ (η<sub>2</sub>, ∞).



## Main result: Risk curve shape (continued)

Suppose 
$$\theta_i^{\star} \stackrel{\text{i.i.d.}}{\sim} \epsilon \mathcal{P}_{M\sqrt{\delta}} + (1-\epsilon)\mathcal{P}_0 \ (SNR = \frac{1}{\sigma^2} \mathbb{E}(\boldsymbol{x}_i^{\top} \boldsymbol{\theta}^{\star})^2 = \frac{\epsilon M^2}{\sigma^2})$$

#### Theorem (Li, W '21)

- there exist two constants  $1 < \eta_1 < \eta_2 < \infty$  st. Risk $(\hat{\theta}^{lnt}; \delta)$ decreases with p/n within the range  $p/n \in (1, \eta_1) \cup (\eta_2, \infty)$ .
- fix  $\epsilon M^2/\sigma^2$ . There exists  $\epsilon^*$  st. if  $\epsilon < \epsilon^*$ , then there exists region within  $(\eta_1, \eta_2)$  st. Risk $(\widehat{\theta}^{\text{Int}}; \delta)$  increases with p/n.





• Why there is a peak at interpolation (p = n)?

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Double descent in condition number, Poggio, Kur and Banburski (2020)

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- Why there exists a second descent (p > n)?

- Why there is a peak at interpolation (p = n)?
- Why there exists a second descent (p > n)? some evidences...
  - Bellec, Lecué and Tsybakov (2016) studies optimal-tuned Lasso

$$\frac{1}{n}\|\widehat{\boldsymbol{\theta}}^{\text{Lasso}} - \boldsymbol{\theta}^{\star}\|_2^2 \leq c\sigma^2 \cdot \kappa(\boldsymbol{X})^2 \cdot \frac{p}{n} \cdot \epsilon \log(\frac{1}{\epsilon})$$

▶ Su and Candés, (2015) studies SLOPE estimator for  $\epsilon \rightarrow 0$ 

$$\frac{1}{n} \| \widehat{\boldsymbol{\theta}}^{\mathsf{SLOPE}} - \boldsymbol{\theta}^\star \|_2^2 \leq 2\sigma^2 \cdot \frac{p}{n} \cdot \epsilon \log(\frac{1}{\epsilon})$$

- Why there is a peak at interpolation (p = n)?
- Why there exists a second descent (p > n)?
- (further increase p/n) wrong support  $\rightarrow$  even worse than the zero estimator



interplay between over-parameterized ratio and sparsity

## Compare to min $\ell_2$ -norm interpolators



Isotropic features

Figure: Hastie et al. (2019)

$$\lim_{\substack{n/p=\delta\\n,p\to\infty}} \operatorname{Risk}(\widehat{\boldsymbol{\theta}}^{\operatorname{Int},\ell_2}) \stackrel{\text{a.s.}}{=} \begin{cases} \frac{\delta}{\delta-1}\sigma^2, & \text{if } \delta = n/p > 1\\ \epsilon M^2(1-\delta) + \frac{1}{1-\delta}\sigma^2, & \text{if } \delta = n/p < 1 \end{cases}$$

# Multi-descent in $\ell_2$ training

Multi-descent in  $\ell_2$  training for different reasons Nakkiran et al. (2020), Chen

et al. (2020), d'Ascoli et al. (2020), Adlam and Pennington (2020), Li and Meng (2020)

- design matrix has heterogenous structures
- non-linear kernels for kernel regression



Figure: Adlam and Pennington (2020)

Our analysis framework

## **Risk characterization**

#### Theorem (Li, Wei '21)

The generalization error of the min  $\ell_1$ -norm interpolator obeys

$$\lim_{\substack{n/p=\delta\\ i, p\to\infty}} \mathsf{Risk}(\widehat{\theta}^{\mathsf{Int}}) \stackrel{\mathrm{a.s.}}{=} \tau^{\star 2}(\delta).$$

— informally coordinates of  $\hat{\theta}^{\text{lnt}}$  behave like  $\eta(\Theta + \tau^{\star}Z; \alpha^{\star}\tau^{\star})$ 

Here  $\eta(x;\zeta) \coloneqq (|x| - \zeta)_+ \operatorname{sign}(x)$ 

 $( au^{\star}, lpha^{\star})$  stands for the unique solution to

$$\begin{aligned} \tau^2 &= \frac{1}{\delta} \mathbb{E} \left[ \left( \eta(\Theta + \tau Z; \alpha \tau) - \Theta \right)^2 \right] + \sigma^2, \\ \delta &= \mathbb{P} \big( \eta(\Theta + \tau Z; \alpha \tau) = 0 \big), \end{aligned}$$

where  $\Theta \sim P_{\Theta}\text{, } Z \sim \mathcal{N}(0,1)$  independent of  $\Theta$ 

### **Descent analysis**

$$(\tau^{\star}, \alpha^{\star})$$
 stands for the unique solution to  
$$\tau^{2} = \frac{1}{\delta} \mathbb{E} \left[ \left( \eta(\Theta + \tau Z; \alpha \tau) - \Theta \right)^{2} \right] + \sigma^{2},$$
$$\delta = \mathbb{P} \big( \eta(\Theta + \tau Z; \alpha \tau) = 0 \big),$$

Suppose  $\Theta \sim \epsilon \mathcal{P}_{M\sqrt{\delta}} + (1-\epsilon)\mathcal{P}_0$ 

$$1 = \frac{\nu^2}{M^2} \sigma^2 + \frac{\epsilon}{\delta} \mathbb{E}\left[\left(\eta(\sqrt{\delta}\nu + Z; \alpha) - \sqrt{\delta}\nu\right)^2\right] + \frac{1 - \epsilon}{\delta} \mathbb{E}\left[\eta^2(Z; \alpha)\right]$$
$$\delta = \epsilon \mathbb{P}\left(|\nu\sqrt{\delta} + Z| > \alpha\right) + (1 - \epsilon)\mathbb{P}(|Z| > \alpha)$$

where  $\nu \coloneqq M/\tau$ 

### **Descent** analysis



Fix  ${\rm SNR}=\frac{\epsilon M^2}{\sigma^2}$  and plot  $\tau^{\star}$  as a function of  $\frac{p}{n}$ 

# Main tool: Approximate message passing (AMP)

#### Theorem (Li, W '21)

The generalization error of the min  $\ell_1$ -norm interpolator obeys

$$\lim_{\substack{n/p=\delta\\ n, p\to\infty}} \mathsf{Risk}(\widehat{\theta}^{\mathsf{Int}}) \stackrel{\mathrm{a.s.}}{=} \tau^{\star 2}(\delta).$$

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 AMP is an efficient iterative algorithm that has been applied to a broad range of statistical estimation problems Donoho Maleki, Montanari, (2009, 2010a, 2011b), Bayati and Montanari (2011)

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**Example:** Solving for Lasso  $(\operatorname{argmin}_{\theta \in \mathbb{R}^p} \frac{1}{2} \| \boldsymbol{y} - \boldsymbol{X} \boldsymbol{\theta} \|_2^2 + \lambda \| \boldsymbol{\theta} \|_1)$ 



Figure credit: Borgerding and Schniter

## **Applications of AMP**

- AMP is successfully applicable in variety of applications
  - imaging Fletcher, Rangan (2014), Vila, Schniter, Meola (2015), Metzler, Mousavi, Baraniuk (2017)
  - communications Schniter (2011), Jeon et al. (2015), Barbier, Krzakala (2017), Rush, Greig, Venkataramanan (2017)

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- in regression and low rank matrix estimation
  - information-theoretically optimal v.s. computationally feasible estimators Reeves, Pfister (2019), Barbier et al. (2019), Lelarge and Miolane (2019)
  - conjectured to have optimal asymptotic estimation error among all polynomial-time algorithms Celentano and Montanari (2019)

— tutorial, Feng, Venkataramanan, Rush, Samworth (2021)

## **Recipe: AMP for statistical procedures**

• dynamics of AMP can be accurately tracked by a simple small-dimensional recursive formula called the *state evolution* 

state evolution:  $\tau_{t+1} = F(\tau_t, \alpha^* \tau_t)$  $(\theta_i^{t+1}, \theta_i^*)_{i=1}^p \stackrel{d}{\approx} (\eta(\Theta + \tau_t Z; \alpha^* \tau_t), \Theta)$ 

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 dynamics of AMP can be accurately tracked by a simple small-dimensional recursive formula called the *state evolution*

 $\begin{array}{ll} \text{state evolution:} & \tau_{t+1} = F(\tau_t, \alpha^* \tau_t) \\ & (\theta_i^{t+1}, \theta_i^*)_{i=1}^p \stackrel{d}{\approx} & (\eta(\Theta + \tau_t Z; \alpha^* \tau_t), \Theta) \end{array}$ 

construct AMP algorithms that converge to ...

M-estimators Donoho and Montanari (2013), Lasso Bayati and Montanari (2011), SLOPE estimator Su and Candés. (2015), MLE for generalized linear model Sur, Chen, Candés (2017), lower-rank matrix estimation Montanari, Venkataramanan (2021), ...

## AMP for min $\ell_1$ interpolator

Illustration of the AMP updates for the minimum  $\ell_1\text{-norm}$  interpolator.



## AMP for min $\ell_1$ interpolator

Illustration of the AMP updates for the minimum  $\ell_1$ -norm interpolator.



• structural property when restricted strongly convexity is lacking

## AMP for min $\ell_1$ interpolator

Illustration of the AMP updates for the minimum  $\ell_1\text{-norm}$  interpolator.



structural property when restricted strongly convexity is lacking

• proper choice of  $\lambda_t$  sequence

$$\mathsf{dist}(\boldsymbol{\theta}^{t+1}, \boldsymbol{\theta}^t) \leq \exp(-\lambda_t) \cdot \mathsf{dist}(\boldsymbol{\theta}^t, \boldsymbol{\theta}^{t-1}) + c |\lambda_t - \lambda_{t+1}|$$

Several extensions and questions...

## **Experiments for non-Gaussian designs**



Figure: The entries of the design matrix  $\sqrt{n}X$  are i.i.d. sampled from the Bernoulli(0.5) distribution for the left, and from  $t(3)/\sqrt{3}$  distribution for the right.

## **Experiments for non-Gaussian designs**



**Figure:** The entries of the design matrix  $\sqrt{n}X$  are i.i.d. sampled from the Bernoulli(0.5) distribution for the left, and from  $t(3)/\sqrt{3}$  distribution for the right.

— universality phenomenon Bayati et al. (2015), Oymak and Tropp (2018), Montanari and Nguyen (2017), Chen and Lam (2021)

## **Experiments for non-Gaussian designs**



Figure: The entries of the design matrix  $\sqrt{n}X$  are i.i.d. sampled from the Bernoulli(0.5) distribution for the left, and from  $t(3)/\sqrt{3}$  distribution for the right.

- universality phenomenon Bayati et al. (2015), Oymak and Tropp (2018), Montanari and Nguyen (2017), Chen and Lam (2021)

- beyond i.i.d design Celentano, Montanari and Wei (2020), Fan (2020)









Mitigating multiple descents: Model-agnostic risk monotonization in high-dimensional learning — ongoing work with Pratik Patil, Arun Kuchibhotla, Alessandro Rinaldo

# **Concluding remarks**



#### **Future directions**

- features with general covariance structure  $\rightarrow$  even more oscillations in risk curve

# **Concluding remarks**



#### **Future directions**

- features with general covariance structure  $\rightarrow$  even more oscillations in risk curve
- generalize to more complex model  $\rightarrow$  towards understanding dnn

#### Thanks for your attention! Questions?

#### Paper:

"Minimum  $\ell_1\text{-norm}$  interpolators: Precise asymptotics and multiple descent," Y. Li, Y. Wei, 2021

"The Lasso with general Gaussian designs with applications to hypothesis testing," M. Celentano, A. Montanari, Y. Wei, 2020

## Linear sparsity

Example: Genome-wide association studies (GWAS): genetic variants  $\rightarrow$  disease

Leading Edge Perspective	Cell	
An Expanded View of Comple From Polygenic to Omnigenic Evan A. Boyle, <sup>1,1</sup> Yang I. Li, <sup>1,4</sup> and Jonathan K. Pritchard <sup>1,2,4*</sup>	ex Traits: C	
Department of Genetics "Department of Biology "Howard Hughes Medical Institute Stanford University, Stanford, CA 94305, USA	matin regions of immune cells (Maurano et al.; 2012; Farh et al., 2015; Kundaje et al., 2015).	
	These observations are generally interpreted in a paradigm in	
	which complex disease is driven by an accumulation of weak	
	effects on the key genes and regulatory pathways that drive	
	disease risk (Furlong, 2013; Chakravarti and Turner, 2016).	
	This model has motivated many stud the functional impacts of individual dise	ies that aim to dissect ase-associated variants

#### Challenge: True signals might NOT be ultra-sparse

 $\longrightarrow$  important features may scale proportionally to the feature dimension
$$\mathcal{F}_{2NN}^{N} = \left\{ f(\boldsymbol{x}, \boldsymbol{a}, \boldsymbol{W}) = \sum_{i=1}^{N} a_{i} \sigma(\langle \boldsymbol{w}_{i}, \boldsymbol{x} \rangle) \mid a_{i} \in \mathbb{R}, \boldsymbol{w}_{i} \in \mathbb{R}^{p}, \forall i \leq N \right\}$$

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Lazy regime: model estimation stays close to initialization

$$\begin{split} &\frac{1}{\epsilon}f(\boldsymbol{x}, \boldsymbol{a}_0 + \epsilon \boldsymbol{a}, \boldsymbol{W}_0 + \epsilon \boldsymbol{W}) \\ &\approx &\frac{1}{\epsilon}f(\boldsymbol{x}, \boldsymbol{a}_0, \boldsymbol{W}_0) + \langle \boldsymbol{a}, \nabla_{\boldsymbol{x}}f(\boldsymbol{x}, \boldsymbol{a}_0, \boldsymbol{W}_0) \rangle + \langle \boldsymbol{W}, \nabla_{\boldsymbol{W}}f(\boldsymbol{x}, \boldsymbol{a}_0, \boldsymbol{W}_0) \rangle \\ &\approx &\frac{1}{\epsilon}f(\boldsymbol{x}, \boldsymbol{a}_0, \boldsymbol{W}_0) + \underbrace{\sum_{i=1}^{N} a_i \sigma(\langle \boldsymbol{w}_{0,i}, x_i \rangle)}_{\text{random feature model}} + \underbrace{\sum_{i=1}^{N} a_{0,i} \langle \boldsymbol{w}_i, x \rangle \sigma(\langle \boldsymbol{w}_{0,i}, x_i \rangle)}_{\text{neural tangent kernel model}} \end{split}$$

$$\mathcal{F}_{2NN}^{N} = \left\{ f(\boldsymbol{x}, \boldsymbol{a}, \boldsymbol{W}) = \sum_{i=1}^{N} a_{i} \sigma(\langle \boldsymbol{w}_{i}, \boldsymbol{x} \rangle) \mid a_{i} \in \mathbb{R}, \boldsymbol{w}_{i} \in \mathbb{R}^{p}, \forall i \leq N \right\}$$

Lazy regime: model estimation stays close to initialization

$$\begin{split} &\frac{1}{\epsilon}f(\boldsymbol{x}, \boldsymbol{a}_0 + \epsilon \boldsymbol{a}, \boldsymbol{W}_0 + \epsilon \boldsymbol{W}) \\ &\approx &\frac{1}{\epsilon}f(\boldsymbol{x}, \boldsymbol{a}_0, \boldsymbol{W}_0) + \langle \boldsymbol{a}, \nabla_{\boldsymbol{a}}f(\boldsymbol{x}, \boldsymbol{a}_0, \boldsymbol{W}_0) \rangle + \langle \boldsymbol{W}, \nabla_{\boldsymbol{W}}f(\boldsymbol{x}, \boldsymbol{a}_0, \boldsymbol{W}_0) \rangle \\ &\approx &\frac{1}{\epsilon}f(\boldsymbol{x}, \boldsymbol{a}_0, \boldsymbol{W}_0) + \underbrace{\sum_{i=1}^{N} a_i \sigma(\langle \boldsymbol{w}_{0,i}, x_i \rangle)}_{\text{random feature model}} + \underbrace{\sum_{i=1}^{N} a_{0,i} \langle \boldsymbol{w}_i, x \rangle \sigma(\langle \boldsymbol{w}_{0,i}, x_i \rangle)}_{\text{neural tangent kernel model}} \end{split}$$

- transform into kernel ridge regression with random kernels!

$$\mathcal{F}_{2NN}^{N} = \left\{ f(\boldsymbol{x}, \boldsymbol{a}, \boldsymbol{W}) = \sum_{i=1}^{N} a_{i} \sigma(\langle \boldsymbol{w}_{i}, \boldsymbol{x} \rangle) \mid a_{i} \in \mathbb{R}, \boldsymbol{w}_{i} \in \mathbb{R}^{p}, \forall i \leq N \right\}$$

Lazy regime: model estimation stays close to initialization

$$\begin{split} &\frac{1}{\epsilon} f(\boldsymbol{x}, \boldsymbol{a}_0 + \epsilon \boldsymbol{a}, \boldsymbol{W}_0 + \epsilon \boldsymbol{W}) \\ &\approx &\frac{1}{\epsilon} f(\boldsymbol{x}, \boldsymbol{a}_0, \boldsymbol{W}_0) + \langle \boldsymbol{a}, \nabla_{\boldsymbol{a}} f(\boldsymbol{x}, \boldsymbol{a}_0, \boldsymbol{W}_0) \rangle + \langle \boldsymbol{W}, \nabla_{\boldsymbol{W}} f(\boldsymbol{x}, \boldsymbol{a}_0, \boldsymbol{W}_0) \rangle \\ &\approx &\frac{1}{\epsilon} f(\boldsymbol{x}, \boldsymbol{a}_0, \boldsymbol{W}_0) + \underbrace{\sum_{i=1}^{N} \boldsymbol{a}_i \sigma(\langle \boldsymbol{w}_{0,i}, x_i \rangle)}_{\text{random feature model}} + \underbrace{\sum_{i=1}^{N} \boldsymbol{a}_{0,i} \langle \boldsymbol{w}_i, x \rangle \sigma(\langle \boldsymbol{w}_{0,i}, x_i \rangle)}_{\text{neural tangent kernel model}} \end{split}$$

#### - transform into kernel ridge regression with random kernels!

Jacob, Gabriel, Hongler (2018), Chizat, Bach (2019), Du et al. (2018), Arora, et al. (2019), Ghorbani, Mei, Misiakiewicz, Montanari (2019), Montanari, Zhong (2020), Allen-Zhu, Li and Liang (2019)...